Formulation of the horizontal pressure gradient force (PGF) in generalized coordinates.

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In a hydrostatic fluid $(\partial \phi/\partial s = -\alpha \partial p/\partial s)$, the layer mass-weighted horizontal pressure gradient force (PGF) satisfies

$$\frac{\partial p}{\partial s} \left[\alpha \nabla_s p + \nabla_s \phi \right] = \nabla_s \left(\frac{\partial p}{\partial s} \alpha p \right) + \frac{\partial}{\partial s} \left(p \nabla_s \phi \right). \tag{1}$$

The 3-dimensional gradient form shown on the right indicates that net accelerations of a fluid system can only be caused by boundary forces. This has well-known implications for vortex spinup/spindown: Given that the curl of the r.h.s. of (1) reduces to

$$\frac{\partial}{\partial s} \left(\nabla_s \times p \nabla_s \phi \right),\,$$

we can state that interface pressure torques governing vortex spinup/spindown in individual s coordinate layers have the form $(\nabla_s \times p \nabla_s \phi)$.

It is important to preserve the above aspects when numerically solving the fluid dynamics equations. The task before us, therefore, is to find a finite-difference expression for the PGF term $[\alpha \nabla_s p + \nabla_s \phi]$ in the horizontal momentum equation that can, after multiplication by the layer thickness, be transformed by finite difference operations into an analog of the right-hand side of (1).

We start by writing the x component of the last term in (1) in the simplest possible, and thus plausibe, form $\delta_s(\bar{p}^x\delta_x\phi)$. Finite-difference product differentiation rules allow this to be expanded as follows:

$$\begin{split} \delta_{s}(\overline{p}^{x}\delta_{x}\phi) &= (\delta_{s}\overline{p}^{x})\delta_{x}\overline{\phi}^{s} + \overline{p}^{xs}\delta_{x}\delta_{s}\phi \\ &= (\delta_{s}\overline{p}^{x})\delta_{x}\overline{\phi}^{s} - \overline{p}^{xs}\delta_{x}(\alpha\delta_{s}p) \\ &= (\delta_{s}\overline{p}^{x})\delta_{x}\overline{\phi}^{s} - \delta_{x}(\overline{p}^{s}\alpha\delta_{s}p) + \overline{\alpha\delta_{s}p}^{x}\delta_{x}\overline{p}^{s} \end{split}$$

A finite-difference equation analogous to (1) is now obtained by rearranging terms and adding an

analogous expression for the y component:

$$\overline{\alpha \delta_s p}^x \delta_x \overline{p}^s + (\delta_s \overline{p}^x) \delta_x \overline{\phi}^s = \delta_x (\overline{p}^s \alpha \delta_s p) + \delta_s (\overline{p}^x \delta_x \phi)$$

$$\overline{\alpha \delta_s p}^y \delta_y \overline{p}^s + (\delta_s \overline{p}^y) \delta_y \overline{\phi}^s = \delta_y \left(\overline{p}^s \alpha \delta_s p \right) + \delta_s (\overline{p}^y \delta_y \phi)$$

The two equations above state that, in order to preserve the conservation properties expressed by (1), the finite-difference PGF must be evaluated in the form

$$\alpha \nabla_{s} p + \nabla_{s} \phi = \begin{pmatrix} \frac{\overline{\alpha \delta_{s} p}^{x}}{\overline{\delta_{s} p}^{x}} \delta_{x} \overline{p}^{s} + \delta_{x} \overline{\phi}^{s} \\ \frac{\overline{\alpha \delta_{s} p}^{y}}{\overline{\delta_{s} p}^{y}} \delta_{y} \overline{p}^{s} + \delta_{y} \overline{\phi}^{s} \end{pmatrix}$$

$$(2)$$

The salient result of our analysis is that writing the undifferentiated factor α in the PGF formula as simply $\overline{\alpha}^x$ or $\overline{\alpha}^y$ can lead to spurious momentum and vorticity generation. To avoid this pitfall, α must appear in the PGF formula in layer thickness-weighted form.

For use in isopycnal or quasi-isopycnals models, it is convenient to express the PGF in terms of the Montgomery potential $M = \phi + p\alpha$. The proper finite-difference analog of M in a staggered vertical grid (p and ϕ carried on layer interfaces, α carried within a layer) is

$$M = \overline{\phi}^s + \alpha \overline{p}^s.$$

The identity $\delta_s(\alpha \overline{p}^s) = \overline{\alpha \delta_s p}^s + p \delta_s \alpha$ allows us to expand the s derivative of M into

$$\delta_s M = p \delta_s \alpha + \overline{\delta_s \phi + \alpha \delta_s p}^s.$$

from which we can extract finite-difference analogs of the two common forms of the hydrostatic equation, $\partial \phi/\partial p = -\alpha$ and $\partial M/\partial \alpha = p$:

$$\partial \phi / \partial p = -\alpha \longrightarrow \delta_s \phi = -\alpha \delta_s p$$

$$\partial M/\partial \alpha = p$$
 \longrightarrow $\delta_s M = p \delta_s \alpha.$

We now write the x component of (2) as

$$\frac{\overline{\alpha\delta_s p}^x}{\overline{\delta_s p}^x} \delta_x \overline{p}^s + \delta_x \overline{\phi}^s = \delta_x M + \left[\frac{\overline{\alpha\delta_s p}^x}{\overline{\delta_s p}^x} \delta_x \overline{p}^s - \delta_x (\alpha \overline{p}^s) \right]. \tag{3}$$

Making use of the relation

$$\overline{AB}^x - \overline{A}^x \overline{B}^x = \frac{1}{4} (\delta_x' A) (\delta_x' B)$$

where δ'_x represents the difference between two neighboring grid points, i.e., $\delta'_x = \Delta x \ \delta_x$, the term in square brackets in (3) can be expanded into

$$\frac{1}{\overline{\delta_s p}^x} \left(\overline{\alpha \delta_s p}^x - \overline{\alpha}^x \overline{\delta_s p}^x \right) \delta_x \overline{p}^s - \overline{p}^{sx} \delta_x \alpha = \frac{1}{4 \overline{\delta_s p}^x} (\delta_x' \delta_s p) (\delta_x' \alpha) \delta_x \overline{p}^s - \overline{p}^{sx} \delta_x \alpha \\
= \frac{1}{4 \overline{\delta_s p}^x} \left[\delta_x' \delta_s p \right) (\delta_x' \overline{p}^s) - 4 \overline{p}^{sx} \delta_s \overline{p}^x \right] \delta_x \alpha.$$

The above expression involves a total of four p points, located one grid distance Δx apart on two consecutive s surfaces. Substantial simplification of this expression is possible by labeling the four points as

$$p_{1} = p\left(x - \frac{\Delta x}{2}, s - \frac{\Delta s}{2}\right)$$

$$p_{2} = p\left(x + \frac{\Delta x}{2}, s - \frac{\Delta s}{2}\right)$$

$$p_{3} = p\left(x - \frac{\Delta x}{2}, s + \frac{\Delta s}{2}\right)$$

$$p_{4} = p\left(x + \frac{\Delta x}{2}, s + \frac{\Delta s}{2}\right).$$

With a modest amount of arithmetic, it can now be shown that the term in square brackets in (3) reduces to

$$\frac{p_1p_2 - p_3p_4}{(p_4 - p_2) + (p_3 - p_1)} \delta_x \alpha.$$

This term, which in combination with the term $\delta_x M$ gives the PGF in x direction, is the sought-after finite-difference analog of $-p\partial\alpha/\partial x$ in

$$\alpha \nabla_s p + \nabla_s \phi = \nabla_s M - p \nabla_s \alpha.$$

The finite difference expression for the PGF in y direction is analogous.